

Introduction to Information Retrieval

<http://informationretrieval.org>

IIR 4: Index Construction

Hinrich Schütze

Center for Information and Language Processing, University of Munich

2014-04-16

Overview

- 1 Recap
- 2 Introduction
- 3 BSBI algorithm
- 4 SPIMI algorithm
- 5 Distributed indexing
- 6 Dynamic indexing

Outline

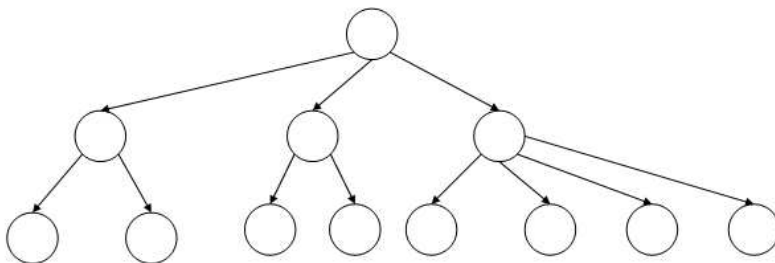
- 1 Recap
- 2 Introduction
- 3 BSBI algorithm
- 4 SPIMI algorithm
- 5 Distributed indexing
- 6 Dynamic indexing

Dictionary as array of fixed-width entries

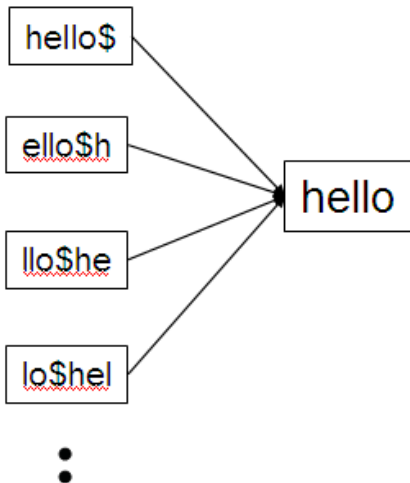
term	document frequency	pointer to postings list
a	656,265	→
aachen	65	→
...
zulu	221	→

space needed: 20 bytes 4 bytes 4 bytes

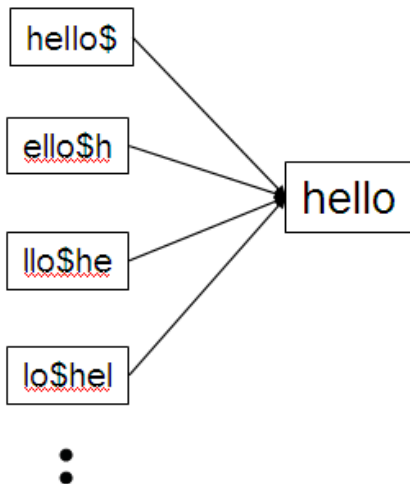
B-tree for looking up entries in array



Wildcard queries using a permuterm index



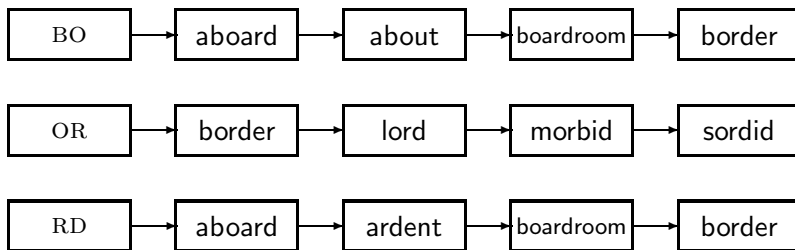
Wildcard queries using a permuterm index



Queries:

- For X, look up X\$
- For X*, look up X*\$
- For *X, look up X\$*
- For *X*, look up X*
- For X*Y, look up Y\$X*

k -gram indexes for spelling correction: *bordroom*



Levenshtein distance for spelling correction

LEVENSHTEINDISTANCE(s_1, s_2)

```
1  for  $i \leftarrow 0$  to  $|s_1|$ 
2  do  $m[i, 0] = i$ 
3  for  $j \leftarrow 0$  to  $|s_2|$ 
4  do  $m[0, j] = j$ 
5  for  $i \leftarrow 1$  to  $|s_1|$ 
6  do for  $j \leftarrow 1$  to  $|s_2|$ 
7      do if  $s_1[i] = s_2[j]$ 
8          then  $m[i, j] = \min\{m[i-1, j] + 1, m[i, j-1] + 1, m[i-1, j-1]\}$ 
9          else  $m[i, j] = \min\{m[i-1, j] + 1, m[i, j-1] + 1, m[i-1, j-1] + 1\}$ 
10 return  $m[|s_1|, |s_2|]$ 
```

Operations: insert, delete, replace, copy

Exercise: Understand Peter Norvig's spelling corrector

```
import re, collections
def words(text): return re.findall('[a-z]+', text.lower())
def train(features):
    model = collections.defaultdict(lambda: 1)
    for f in features:
        model[f] += 1
    return model
NWORDS = train(words(file('big.txt').read()))
alphabet = 'abcdefghijklmnopqrstuvwxyz'
def edits1(word):
    splits      = [(word[:i], word[i:]) for i in range(len(word) + 1)]
    deletes     = [a + b[1:] for a, b in splits if b]
    transposes  = [a + b[1] + b[0] + b[2:] for a, b in splits if len(b) > 1]
    replaces    = [a + c + b[1:] for a, b in splits for c in alphabet if b]
    inserts     = [a + c + b      for a, b in splits for c in alphabet]
    return set(deletes + transposes + replaces + inserts)
def known_edits2(word):
    return set(e2 for e1 in edits1(word) for e2 in
        edits1(e1) if e2 in NWORDS)
def known(words): return set(w for w in words if w in NWORDS)
def correct(word):
    candidates = known([word]) or known(edits1(word)) or
        known_edits2(word) or [word]
    return max(candidates, key=NWORDS.get)
```

Take-away

Take-away

- Two index construction algorithms: **BSBI** (simple) and **SPIMI** (more realistic)

Take-away

- Two index construction algorithms: **BSBI** (simple) and **SPIMI** (more realistic)
- **Distributed** index construction: MapReduce

Take-away

- Two index construction algorithms: **BSBI** (simple) and **SPIMI** (more realistic)
- **Distributed** index construction: MapReduce
- **Dynamic** index construction: how to keep the index up-to-date as the collection changes

Outline

- 1 Recap
- 2 Introduction**
- 3 BSBI algorithm
- 4 SPIMI algorithm
- 5 Distributed indexing
- 6 Dynamic indexing

Hardware basics

Hardware basics

- Many design decisions in information retrieval are based on hardware constraints.

Hardware basics

- Many design decisions in information retrieval are based on hardware constraints.
- We begin by reviewing hardware basics that we'll need in this course.

Hardware basics

Hardware basics

- Access to data is much faster in memory than on disk.
(roughly a factor of 10)

Hardware basics

- Access to data is much **faster in memory than on disk**.
(roughly a factor of 10)
- **Disk seeks are “idle” time**: No data is transferred from disk while the disk head is being positioned.

Hardware basics

- Access to data is much faster in memory than on disk.
(roughly a factor of 10)
- Disk seeks are “idle” time: No data is transferred from disk while the disk head is being positioned.
- To optimize transfer time from disk to memory: one large chunk is faster than many small chunks.

Hardware basics

- Access to data is much **faster in memory than on disk**. (roughly a factor of 10)
- **Disk seeks are “idle” time**: No data is transferred from disk while the disk head is being positioned.
- To optimize transfer time from disk to memory: **one large chunk is faster than many small chunks**.
- **Disk I/O is block-based**: Reading and writing of entire blocks (as opposed to smaller chunks). Block sizes: 8KB to 256 KB

Hardware basics

- Access to data is much **faster in memory than on disk**.
(roughly a factor of 10)
- **Disk seeks are “idle” time**: No data is transferred from disk while the disk head is being positioned.
- To optimize transfer time from disk to memory: **one large chunk is faster than many small chunks**.
- **Disk I/O is block-based**: Reading and writing of entire blocks (as opposed to smaller chunks). Block sizes: 8KB to 256 KB
- Servers used in IR systems typically have many **GBs of main memory** and **TBs of disk space**.

Hardware basics

- Access to data is much **faster in memory than on disk**. (roughly a factor of 10)
- **Disk seeks are “idle” time**: No data is transferred from disk while the disk head is being positioned.
- To optimize transfer time from disk to memory: **one large chunk is faster than many small chunks**.
- **Disk I/O is block-based**: Reading and writing of entire blocks (as opposed to smaller chunks). Block sizes: 8KB to 256 KB
- Servers used in IR systems typically have many **GBs of main memory** and **TBs of disk space**.
- **Fault tolerance is expensive**: It's cheaper to use many regular machines than one fault tolerant machine.

Some stats (ca. 2008)

symbol	statistic	value
s	average seek time	5 ms = 5×10^{-3} s
b	transfer time per byte	$0.02 \mu\text{s} = 2 \times 10^{-8}$ s
	processor's clock rate	10^9 s^{-1}
p	lowlevel operation (e.g., compare & swap a word)	$0.01 \mu\text{s} = 10^{-8}$ s
	size of main memory	several GB
	size of disk space	1 TB or more

RCV1 collection

RCV1 collection

- Shakespeare's collected works are not large enough for demonstrating many of the points in this course.

RCV1 collection

- Shakespeare's collected works are not large enough for demonstrating many of the points in this course.
- As an example for applying scalable index construction algorithms, we will use the [Reuters RCV1](#) collection.

RCV1 collection

- Shakespeare's collected works are not large enough for demonstrating many of the points in this course.
- As an example for applying scalable index construction algorithms, we will use the [Reuters RCV1](#) collection.
- English newswire articles sent over the wire in 1995 and 1996 (one year).

A Reuters RCV1 document



You are here: [Home](#) > [News](#) > [Science](#) > [Article](#)

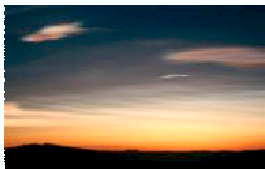
Go to a Section: [U.S.](#) [International](#) [Business](#) [Markets](#) [Politics](#) [Entertainment](#) [Technology](#) [Sports](#) [Oddly Enough](#)

Extreme conditions create rare Antarctic clouds

Tue Aug 1, 2006 3:20am ET

[Email This Article](#) | [Print This Article](#) | [Reprint](#)

[-] Text [+]



SYDNEY (Reuters) - Rare, mother-of-pearl colored clouds caused by extreme weather conditions above Antarctica are a possible indication of global warming, Australian scientists said on Tuesday.

Known as nacreous clouds, the spectacular formations showing delicate wisps of colors were photographed in the sky over an Australian

Reuters RCV1 statistics

N	documents	800,000
L	tokens per document	200
M	terms (= word types)	400,000
	bytes per token (incl. spaces/punct.)	6
	bytes per token (without spaces/punct.)	4.5
	bytes per term (= word type)	7.5
T	non-positional postings	100,000,000

Reuters RCV1 statistics

N	documents	800,000
L	tokens per document	200
M	terms (= word types)	400,000
	bytes per token (incl. spaces/punct.)	6
	bytes per token (without spaces/punct.)	4.5
	bytes per term (= word type)	7.5
T	non-positional postings	100,000,000

Exercise: Average frequency of a term (how many tokens)? 4.5
bytes per word token vs. 7.5 bytes per word type: why the
difference? How many positional postings?

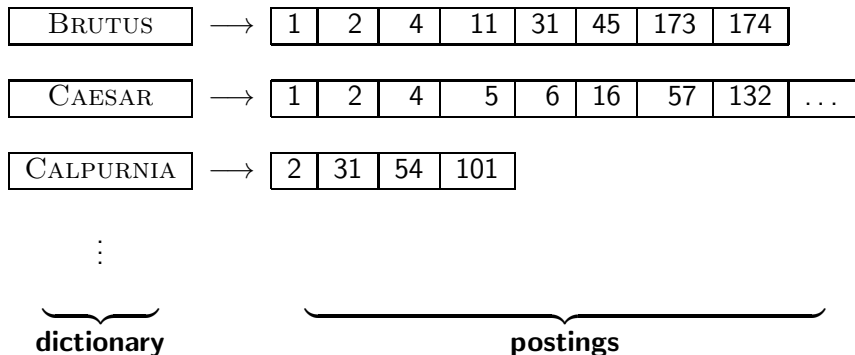
Exercise

Why does this algorithm not scale to very large collections?

Outline

- 1 Recap
- 2 Introduction
- 3 BSBI algorithm**
- 4 SPIMI algorithm
- 5 Distributed indexing
- 6 Dynamic indexing

Goal: construct the inverted index



Index construction in IIR 1: Sort postings in memory

term	docID		term	docID
I	1		ambitious	2
did	1		be	2
enact	1		brutus	1
julius	1		brutus	2
caesar	1		capitol	1
I	1		caesar	1
was	1		caesar	2
killed	1		caesar	2
i'	1		did	1
the	1		enact	1
capitol	1		hath	1
brutus	1		I	1
killed	1		I	1
me	1	⇒	i'	1
so	2		it	2
let	2		julius	1
it	2		killed	1
be	2		killed	1
with	2		let	2
caesar	2		me	1
the	2		noble	2
noble	2		so	2
brutus	2		the	1
hath	2		the	2
told	2		told	2
you	2		you	2
caesar	2		was	1
was	2		was	2
ambitious	2		with	2

Sort-based index construction

Sort-based index construction

- As we build index, we parse docs one at a time.

Sort-based index construction

- As we build index, we parse docs one at a time.
- The final postings for any term are incomplete until the end.

Sort-based index construction

- As we build index, we parse docs one at a time.
- The final postings for any term are incomplete until the end.
- Can we keep all postings in memory and then do the sort in-memory at the end?

Sort-based index construction

- As we build index, we parse docs one at a time.
- The final postings for any term are incomplete until the end.
- Can we keep all postings in memory and then do the sort in-memory at the end?
- No, not for large collections

Sort-based index construction

- As we build index, we parse docs one at a time.
- The final postings for any term are incomplete until the end.
- Can we keep all postings in memory and then do the sort in-memory at the end?
- No, not for large collections
- Thus: We need to store intermediate results on disk.

Same algorithm for disk?

Same algorithm for disk?

- Can we use the same index construction algorithm for larger collections, but by using disk instead of memory?

Same algorithm for disk?

- Can we use the same index construction algorithm for larger collections, but by using disk instead of memory?
- No: Sorting very large sets of records on disk is too slow – too many disk seeks.

Same algorithm for disk?

- Can we use the same index construction algorithm for larger collections, but by using disk instead of memory?
- No: Sorting very large sets of records on disk is too slow – too many disk seeks.
- We need an **external** sorting algorithm.

“External” sorting algorithm (using few disk seeks)

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
 - Each posting has size 12 bytes (4+4+4: termID, docID, term frequency).

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
 - Each posting has size 12 bytes (4+4+4: termID, docID, term frequency).
- Define a **block** to consist of 10,000,000 such postings

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
 - Each posting has size 12 bytes (4+4+4: termID, docID, term frequency).
- Define a **block** to consist of 10,000,000 such postings
 - We can easily fit that many postings into memory.

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
 - Each posting has size 12 bytes (4+4+4: termID, docID, term frequency).
- Define a **block** to consist of 10,000,000 such postings
 - We can easily fit that many postings into memory.
 - We will have 10 such blocks for RCV1.

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
 - Each posting has size 12 bytes (4+4+4: termID, docID, term frequency).
- Define a **block** to consist of 10,000,000 such postings
 - We can easily fit that many postings into memory.
 - We will have 10 such blocks for RCV1.
- Basic idea of algorithm:

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
 - Each posting has size 12 bytes (4+4+4: termID, docID, term frequency).
- Define a **block** to consist of 10,000,000 such postings
 - We can easily fit that many postings into memory.
 - We will have 10 such blocks for RCV1.
- Basic idea of algorithm:
 - For each block: (i) accumulate postings, (ii) sort in memory, (iii) write to disk

“External” sorting algorithm (using few disk seeks)

- We must sort $T = 100,000,000$ non-positional postings.
 - Each posting has size 12 bytes (4+4+4: termID, docID, term frequency).
- Define a **block** to consist of 10,000,000 such postings
 - We can easily fit that many postings into memory.
 - We will have 10 such blocks for RCV1.
- Basic idea of algorithm:
 - For each block: (i) accumulate postings, (ii) sort in memory, (iii) write to disk
 - Then merge the blocks into one long sorted order.

Merging two blocks

postings
to be merged

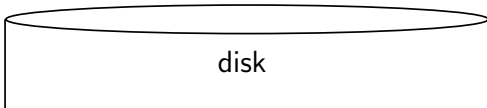
Block 1	
brutus	d3
caesar	d4
noble	d3
with	d4

Block 2	
brutus	d2
caesar	d1
julius	d1
killed	d2



brutus	d2
brutus	d3
caesar	d1
caesar	d4
julius	d1
killed	d2
noble	d3
with	d4

merged
postings



Blocked Sort-Based Indexing

BSBIINDEXCONSTRUCTION()

```
1   $n \leftarrow 0$ 
2  while (all documents have not been processed)
3  do  $n \leftarrow n + 1$ 
4       $block \leftarrow \text{PARSENEXTBLOCK}()$ 
5       $\text{BSBI-INVERT}(block)$ 
6       $\text{WRITEBLOCKTODISK}(block, f_n)$ 
7   $\text{MERGEBLOCKS}(f_1, \dots, f_n; f_{\text{merged}})$ 
```

Outline

- 1 Recap
- 2 Introduction
- 3 BSBI algorithm
- 4 SPIMI algorithm**
- 5 Distributed indexing
- 6 Dynamic indexing

Problem with sort-based algorithm

Problem with sort-based algorithm

- Our assumption was: we can keep the dictionary in memory.

Problem with sort-based algorithm

- Our assumption was: we can keep the dictionary in memory.
- We need the dictionary (which grows dynamically) in order to implement a term to termID mapping.

Problem with sort-based algorithm

- Our assumption was: we can keep the dictionary in memory.
- We need the dictionary (which grows dynamically) in order to implement a term to termID mapping.
- Actually, we could work with term,docID postings instead of termID,docID postings . . .

Problem with sort-based algorithm

- Our assumption was: we can keep the dictionary in memory.
- We need the dictionary (which grows dynamically) in order to implement a term to termID mapping.
- Actually, we could work with term,docID postings instead of termID,docID postings . . .
- . . . but then intermediate files become very large. (We would end up with a scalable, but very slow index construction method.)

Single-pass in-memory indexing

Single-pass in-memory indexing

- Abbreviation: SPIMI

Single-pass in-memory indexing

- Abbreviation: SPIMI
- Key idea 1: Generate separate dictionaries for each block – no need to maintain term-termID mapping across blocks.

Single-pass in-memory indexing

- Abbreviation: SPIMI
- Key idea 1: Generate separate dictionaries for each block – no need to maintain term-termID mapping across blocks.
- Key idea 2: Don't sort. Accumulate postings in postings lists as they occur.

Single-pass in-memory indexing

- Abbreviation: SPIMI
- Key idea 1: Generate separate dictionaries for each block – no need to maintain term-termID mapping across blocks.
- Key idea 2: Don't sort. Accumulate postings in postings lists as they occur.
- With these two ideas we can generate a complete inverted index for each block.

Single-pass in-memory indexing

- Abbreviation: SPIMI
- Key idea 1: Generate separate dictionaries for each block – no need to maintain term-termID mapping across blocks.
- Key idea 2: Don't sort. Accumulate postings in postings lists as they occur.
- With these two ideas we can generate a complete inverted index for each block.
- These separate indexes can then be merged into one big index.

SPIMI-Invert

SPIMI-INVERT(*token_stream*)

```
1  output_file  $\leftarrow$  NEWFILE()
2  dictionary  $\leftarrow$  NEWHASH()
3  while (free memory available)
4  do token  $\leftarrow$  next(token_stream)
5      if term(token)  $\notin$  dictionary
6          then postings_list  $\leftarrow$  ADDTODICTIONARY(dictionary,term(token))
7          else postings_list  $\leftarrow$  GETPOSTINGSLIST(dictionary,term(token))
8          if full(postings_list)
9              then postings_list  $\leftarrow$  DOUBLEPOSTINGSLIST(dictionary,term(token))
10         ADDTOPOSTINGSLIST(postings_list,docID(token))
11 sorted_terms  $\leftarrow$  SORTTERMS(dictionary)
12 WRITEBLOCKTODISK(sorted_terms,dictionary,output_file)
13 return output_file
```

SPIMI-Invert

```
SPIMI-INVERT(token_stream)
1  output_file  $\leftarrow$  NEWFILE()
2  dictionary  $\leftarrow$  NEWHASH()
3  while (free memory available)
4  do token  $\leftarrow$  next(token_stream)
5      if term(token)  $\notin$  dictionary
6          then postings_list  $\leftarrow$  ADDTODICTIONARY(dictionary,term(token))
7          else postings_list  $\leftarrow$  GETPOSTINGSLIST(dictionary,term(token))
8          if full(postings_list)
9              then postings_list  $\leftarrow$  DOUBLEPOSTINGSLIST(dictionary,term(token))
10         ADDTOPOSTINGSLIST(postings_list,docID(token))
11  sorted_terms  $\leftarrow$  SORTTERMS(dictionary)
12  WRITEBLOCKTODISK(sorted_terms,dictionary,output_file)
13  return output_file
```

Merging of blocks is analogous to BSBI.

SPIMI: Compression

SPIMI: Compression

- Compression makes SPIMI even more efficient.

SPIMI: Compression

- Compression makes SPIMI even more efficient.
 - Compression of terms

SPIMI: Compression

- Compression makes SPIMI even more efficient.
 - Compression of terms
 - Compression of postings

SPIMI: Compression

- Compression makes SPIMI even more efficient.
 - Compression of terms
 - Compression of postings
 - See next lecture

Outline

- 1 Recap
- 2 Introduction
- 3 BSBI algorithm
- 4 SPIMI algorithm
- 5 Distributed indexing**
- 6 Dynamic indexing

Distributed indexing

Distributed indexing

- For web-scale indexing (don't try this at home!): must use a distributed computer cluster

Distributed indexing

- For web-scale indexing (don't try this at home!): must use a distributed computer cluster
- Individual machines are fault-prone.

Distributed indexing

- For web-scale indexing (don't try this at home!): must use a distributed computer cluster
- Individual machines are fault-prone.
 - Can unpredictably slow down or fail.

Distributed indexing

- For web-scale indexing (don't try this at home!): must use a distributed computer cluster
- Individual machines are fault-prone.
 - Can unpredictably slow down or fail.
- How do we exploit such a pool of machines?

Google data centers (2007 estimates; Gartner)

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.
- Based on expenditures of 200–250 million dollars per year

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.
- Based on expenditures of 200–250 million dollars per year
- This would be 10% of the computing capacity of the world!

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.
- Based on expenditures of 200–250 million dollars per year
- This would be 10% of the computing capacity of the world!
- If in a non-fault-tolerant system with 1000 nodes, each node has 99.9% uptime, what is the uptime of the system (assuming it does not tolerate failures)?

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.
- Based on expenditures of 200–250 million dollars per year
- This would be 10% of the computing capacity of the world!
- If in a non-fault-tolerant system with 1000 nodes, each node has 99.9% uptime, what is the uptime of the system (assuming it does not tolerate failures)?
- Answer: 37%

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.
- Based on expenditures of 200–250 million dollars per year
- This would be 10% of the computing capacity of the world!
- If in a non-fault-tolerant system with 1000 nodes, each node has 99.9% uptime, what is the uptime of the system (assuming it does not tolerate failures)?
- Answer: 37%
- Suppose a server will fail after 3 years. For an installation of 1 million servers, what is the interval between machine failures?

Google data centers (2007 estimates; Gartner)

- Google data centers mainly contain commodity machines.
- Data centers are distributed all over the world.
- 1 million servers, 3 million processors/cores
- Google installs 100,000 servers each quarter.
- Based on expenditures of 200–250 million dollars per year
- This would be 10% of the computing capacity of the world!
- If in a non-fault-tolerant system with 1000 nodes, each node has 99.9% uptime, what is the uptime of the system (assuming it does not tolerate failures)?
- Answer: 37%
- Suppose a server will fail after 3 years. For an installation of 1 million servers, what is the interval between machine failures?
- Answer: less than two minutes

Distributed indexing

Distributed indexing

- Maintain a **master** machine directing the indexing job – considered “safe”

Distributed indexing

- Maintain a **master** machine directing the indexing job – considered “safe”
- Break up indexing into sets of parallel tasks

Distributed indexing

- Maintain a **master** machine directing the indexing job – considered “safe”
- Break up indexing into sets of parallel tasks
- Master machine assigns each task to an idle machine from a pool.

Parallel tasks

Parallel tasks

- We will define two sets of parallel tasks and deploy two types of machines to solve them:

Parallel tasks

- We will define two sets of parallel tasks and deploy two types of machines to solve them:
 - Parsers

Parallel tasks

- We will define two sets of parallel tasks and deploy two types of machines to solve them:
 - Parsers
 - Inverters

Parallel tasks

- We will define two sets of parallel tasks and deploy two types of machines to solve them:
 - Parsers
 - Inverters
- Break the input document collection into **splits** (corresponding to blocks in BSBI/SPIMI)

Parallel tasks

- We will define two sets of parallel tasks and deploy two types of machines to solve them:
 - Parsers
 - Inverters
- Break the input document collection into **splits** (corresponding to blocks in BSBI/SPIMI)
- Each split is a subset of documents.

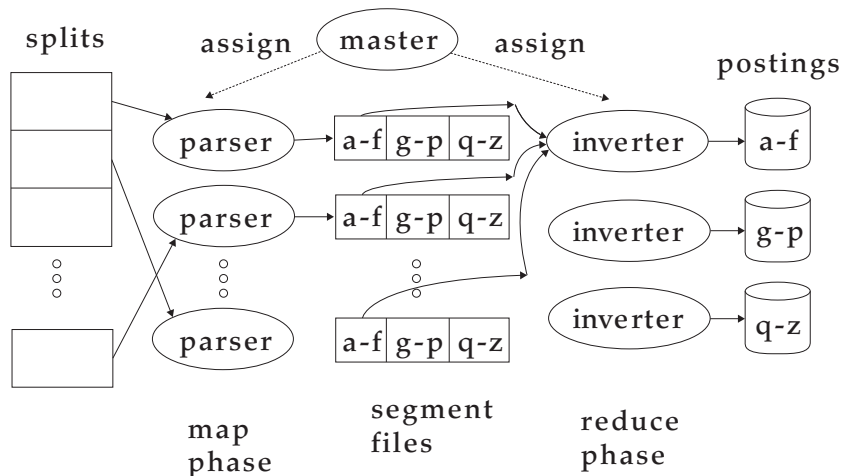
Parsers

- Master assigns a split to an idle parser machine.
- Parser reads a document at a time and **emits** (term,docID)-pairs.
- Parser writes pairs into j term-partitions.
- Each for a range of terms' first letters
 - E.g., a-f, g-p, q-z (here: $j = 3$)

Inverters

- An inverter collects all (term,docID) pairs (= postings) for one term-partition (e.g., for a-f).
- Sorts and writes to postings lists

Data flow



MapReduce

MapReduce

- The index construction algorithm we just described is an instance of MapReduce.

MapReduce

- The index construction algorithm we just described is an instance of MapReduce.
- MapReduce is a robust and conceptually simple framework for distributed computing ...

MapReduce

- The index construction algorithm we just described is an instance of MapReduce.
- MapReduce is a robust and conceptually simple framework for distributed computing ...
- ...without having to write code for the distribution part.

MapReduce

- The index construction algorithm we just described is an instance of MapReduce.
- MapReduce is a robust and conceptually simple framework for distributed computing ...
- ... without having to write code for the distribution part.
- The Google indexing system (ca. 2002) consisted of a number of phases, each implemented in MapReduce.

MapReduce

- The index construction algorithm we just described is an instance of MapReduce.
- MapReduce is a robust and conceptually simple framework for distributed computing ...
- ... without having to write code for the distribution part.
- The Google indexing system (ca. 2002) consisted of a number of phases, each implemented in MapReduce.
- Index construction was just one phase.

MapReduce

- The index construction algorithm we just described is an instance of MapReduce.
- MapReduce is a robust and conceptually simple framework for distributed computing ...
- ... without having to write code for the distribution part.
- The Google indexing system (ca. 2002) consisted of a number of phases, each implemented in MapReduce.
- Index construction was just one phase.
- Another phase: transform term-partitioned into document-partitioned index.

MapReduce

- The index construction algorithm we just described is an instance of MapReduce.
- MapReduce is a robust and conceptually simple framework for distributed computing ...
- ... without having to write code for the distribution part.
- The Google indexing system (ca. 2002) consisted of a number of phases, each implemented in MapReduce.
- Index construction was just one phase.
- Another phase: transform term-partitioned into document-partitioned index.
- Why might a document-partitioned index be preferable?

Index construction in MapReduce

Schema of map and reduce functions

map: input $\rightarrow \text{list}(k, v)$
 reduce: $(k, \text{list}(v)) \rightarrow \text{output}$

Instantiation of the schema for index construction

map: web collection $\rightarrow \text{list}(\text{termID}, \text{docID})$
 reduce: $((\text{termID}_1, \text{list}(\text{docID})), (\text{termID}_2, \text{list}(\text{docID})), \dots) \rightarrow (\text{postings_list}_1, \text{postings_list}_2, \dots)$

Example for index construction

map: $d_2 : C \text{ DIED}, d_1 : C \text{ CAME}, C \text{ C'ED} \rightarrow ((C, d_2), (DIED, d_2), (C, d_1), (CAME, d_1), (C, d_1), (C'ED, d_1))$
 reduce: $((C, (d_2, d_1, d_1)), (DIED, (d_2)), (CAME, (d_1)), (C'ED, (d_1))) \rightarrow ((C, (d_1:2, d_2:1)), (DIED, (d_2:1)), (CAME, (d_1:1)), (C'ED, (d_1:1)))$

Exercise

- What information does the task description contain that the master gives to a parser?
- What information does the parser report back to the master upon completion of the task?
- What information does the task description contain that the master gives to an inverter?
- What information does the inverter report back to the master upon completion of the task?

Outline

- 1 Recap
- 2 Introduction
- 3 BSBI algorithm
- 4 SPIMI algorithm
- 5 Distributed indexing
- 6 Dynamic indexing

Dynamic indexing

Dynamic indexing

- Up to now, we have assumed that collections are **static**.

Dynamic indexing

- Up to now, we have assumed that collections are **static**.
- They rarely are: Documents are inserted, deleted and modified.

Dynamic indexing

- Up to now, we have assumed that collections are **static**.
- They rarely are: Documents are inserted, deleted and modified.
- This means that the dictionary and postings lists have to be **dynamically** modified.

Dynamic indexing: Simplest approach

Dynamic indexing: Simplest approach

- Maintain big main index on disk

Dynamic indexing: Simplest approach

- Maintain **big main index on disk**
- New docs go into **small auxiliary index in memory**.

Dynamic indexing: Simplest approach

- Maintain **big main index on disk**
- New docs go into **small auxiliary index in memory**.
- Search across both, merge results

Dynamic indexing: Simplest approach

- Maintain **big main index on disk**
- New docs go into **small auxiliary index in memory**.
- Search across both, merge results
- Periodically, merge auxiliary index into big index

Dynamic indexing: Simplest approach

- Maintain **big main index on disk**
- New docs go into **small auxiliary index in memory**.
- Search across both, merge results
- Periodically, merge auxiliary index into big index
- Deletions:

Dynamic indexing: Simplest approach

- Maintain **big main index on disk**
- New docs go into **small auxiliary index in memory**.
- Search across both, merge results
- Periodically, merge auxiliary index into big index
- Deletions:
 - Invalidation bit-vector for deleted docs

Dynamic indexing: Simplest approach

- Maintain **big main index on disk**
- New docs go into **small auxiliary index in memory**.
- Search across both, merge results
- Periodically, merge auxiliary index into big index
- Deletions:
 - Invalidation bit-vector for deleted docs
 - Filter docs returned by index using this bit-vector

Issue with auxiliary and main index

Issue with auxiliary and main index

- Frequent merges

Issue with auxiliary and main index

- Frequent merges
- Poor search performance during index merge

Logarithmic merge

Logarithmic merge

- Logarithmic merging amortizes the cost of merging indexes over time.

Logarithmic merge

- Logarithmic merging amortizes the cost of merging indexes over time.
 - → Users see smaller effect on response times.

Logarithmic merge

- Logarithmic merging amortizes the cost of merging indexes over time.
 - → Users see smaller effect on response times.
- Maintain a series of indexes, each twice as large as the previous one.

Logarithmic merge

- Logarithmic merging amortizes the cost of merging indexes over time.
 - → Users see smaller effect on response times.
- Maintain a series of indexes, each twice as large as the previous one.
- Keep smallest (Z_0) in memory

Logarithmic merge

- Logarithmic merging amortizes the cost of merging indexes over time.
 - \rightarrow Users see smaller effect on response times.
- Maintain a series of indexes, each twice as large as the previous one.
- Keep smallest (Z_0) in memory
- Larger ones (I_0, I_1, \dots) on disk

Logarithmic merge

- Logarithmic merging amortizes the cost of merging indexes over time.
 - \rightarrow Users see smaller effect on response times.
- Maintain a series of indexes, each twice as large as the previous one.
- Keep smallest (Z_0) in memory
- Larger ones (I_0, I_1, \dots) on disk
- If Z_0 gets too big ($> n$), write to disk as I_0

Logarithmic merge

- Logarithmic merging amortizes the cost of merging indexes over time.
 - \rightarrow Users see smaller effect on response times.
- Maintain a series of indexes, each twice as large as the previous one.
- Keep smallest (Z_0) in memory
- Larger ones (l_0, l_1, \dots) on disk
- If Z_0 gets too big ($> n$), write to disk as l_0
- ... or merge with l_0 (if l_0 already exists) and write merger to l_1 etc.

LMERGEADDTOKEN(*indexes*, Z_0 , *token*)

```

1   $Z_0 \leftarrow \text{MERGE}(Z_0, \{\text{token}\})$ 
2  if  $|Z_0| = n$ 
3    then for  $i \leftarrow 0$  to  $\infty$ 
4      do if  $l_i \in \text{indexes}$ 
5        then  $Z_{i+1} \leftarrow \text{MERGE}(l_i, Z_i)$ 
6          ( $Z_{i+1}$  is a temporary index on disk.)
7           $\text{indexes} \leftarrow \text{indexes} - \{l_i\}$ 
8        else  $l_i \leftarrow Z_i$  ( $Z_i$  becomes the permanent index  $l_i$ .)
9           $\text{indexes} \leftarrow \text{indexes} \cup \{l_i\}$ 
10       BREAK
11      $Z_0 \leftarrow \emptyset$ 

```

LOGARITHMICMERGE()

```

1   $Z_0 \leftarrow \emptyset$  ( $Z_0$  is the in-memory index.)
2   $\text{indexes} \leftarrow \emptyset$ 
3  while true
4    do LMERGEADDTOKEN(indexes,  $Z_0$ , GETNEXTTOKEN())

```

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101
- 0110

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101
- 0110
- 0111

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101
- 0110
- 0111
- 1000

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101
- 0110
- 0111
- 1000
- 1001

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101
- 0110
- 0111
- 1000
- 1001
- 1010

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101
- 0110
- 0111
- 1000
- 1001
- 1010
- 1011

Binary numbers: $l_3l_2l_1l_0 = 2^32^22^12^0$

- 0001
- 0010
- 0011
- 0100
- 0101
- 0110
- 0111
- 1000
- 1001
- 1010
- 1011
- 1100

Logarithmic merge

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)
- So query processing requires the merging of $O(\log T)$ indexes

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)
- So query processing requires the merging of $O(\log T)$ indexes
- Time complexity of index construction is $O(T \log T)$.

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)
- So query processing requires the merging of $O(\log T)$ indexes
- Time complexity of index construction is $O(T \log T)$.
 - ...because each of T postings is merged $O(\log T)$ times.

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)
- So query processing requires the merging of $O(\log T)$ indexes
- Time complexity of index construction is $O(T \log T)$.
 - ... because each of T postings is merged $O(\log T)$ times.
- Auxiliary index: index construction time is $O(T^2)$ as each posting is touched in each merge.

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)
- So query processing requires the merging of $O(\log T)$ indexes
- Time complexity of index construction is $O(T \log T)$.
 - ... because each of T postings is merged $O(\log T)$ times.
- Auxiliary index: index construction time is $O(T^2)$ as each posting is touched in each merge.
 - Suppose auxiliary index has size a

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)
- So query processing requires the merging of $O(\log T)$ indexes
- Time complexity of index construction is $O(T \log T)$.
 - ... because each of T postings is merged $O(\log T)$ times.
- Auxiliary index: index construction time is $O(T^2)$ as each posting is touched in each merge.
 - Suppose auxiliary index has size a
 - $a + 2a + 3a + 4a + \dots + na = a \frac{n(n+1)}{2} = O(n^2)$

Logarithmic merge

- Number of indexes bounded by $O(\log T)$ (T is total number of postings read so far)
- So query processing requires the merging of $O(\log T)$ indexes
- Time complexity of index construction is $O(T \log T)$.
 - ... because each of T postings is merged $O(\log T)$ times.
- Auxiliary index: index construction time is $O(T^2)$ as each posting is touched in each merge.
 - Suppose auxiliary index has size a
 - $a + 2a + 3a + 4a + \dots + na = a \frac{n(n+1)}{2} = O(n^2)$
- So logarithmic merging is an order of magnitude more efficient.

Dynamic indexing at large search engines

Dynamic indexing at large search engines

- Often a combination

Dynamic indexing at large search engines

- Often a combination
 - Frequent incremental changes

Dynamic indexing at large search engines

- Often a combination
 - Frequent incremental changes
 - Rotation of large parts of the index that can then be swapped in

Dynamic indexing at large search engines

- Often a combination
 - Frequent incremental changes
 - Rotation of large parts of the index that can then be swapped in
 - Occasional complete rebuild (becomes harder with increasing size – not clear if Google can do a complete rebuild)

Building positional indexes

Building positional indexes

- Basically the same problem except that the intermediate data structures are large.

Take-away

- Two index construction algorithms: **BSBI** (simple) and **SPIMI** (more realistic)
- **Distributed** index construction: MapReduce
- **Dynamic** index construction: how to keep the index up-to-date as the collection changes

Resources

- Chapter 4 of IIR
- Resources at <http://cislmu.org>
 - Original publication on MapReduce by Dean and Ghemawat (2004)
 - Original publication on SPIMI by Heinz and Zobel (2003)
 - YouTube video: Google data centers